

**In the Specification:**

Please amend the Specification, the paragraph beginning at line 1 of page 17 as follows:

Since the motor 9 can follow the control signal Rmot substantially without delay, it is only necessary for the correction table 12 to compensate characteristics from the motor 9 to the bend angle of the distal bending section 2. In the motorized endoscope, none of the wires 4 and 5 ~~are does not become~~ loose in a neutral reference position where the distal bending section 2 is not bent in the vertical direction. However, if the wires 4 and 5 extend with time, both the wires 4 and 5 become loose in some cases in an initial state (neutral reference position) in which the distal bending section 2 is not bent in the vertical direction. In such as state, even if attempt is made to bend the distal bending section 2 in any of upper and lower directions, the distal bending section 2 is not bent until the motor 9 is rotated to a position where the slack of the wire in that direction is resolved. The correction table 12 is arranged such that the table compensates characteristics in a predetermined range of the neutral reference position